

# InMax – Revolution

Electrical, industrial quarter turn actuators size M

Contol 0...10 VDC, 4...20 mA, 24...240 VAC/DC, 95° Angle of rotation incl. 5° pretention  
50/75 Nm - 100 Nm without and 30 Nm - 50 Nm with safety operation (spring return)

InMax-	50.75 - Y
InMax-	100 - Y
InMax-	30 - YF
InMax-	50 - YF
InMax-	... - CTM

Subject to change!

**Compact. Easy installation. Universal. Cost effective. Safe.**

Type	Torque	Supply	Motor running time	Spring return	Control mode	Feedback	Wiring diagram
InMax-50.75 - Y	50 Nm & 75 Nm	24..240 VAC/DC	40/60/90/120/150 sec. at 90°	without	3-pos, 0...10 VDC, 4...20 mA	0...10 VDC, 4...20 mA	SB 4.0
InMax- 100 - Y	100 Nm	24..240 VAC/DC	40/60/90/120/150 sec. at 90°	without	3-pos, 0...10 VDC, 4...20 mA	0...10 VDC, 4...20 mA	SB 4.0
InMax- 30 - YF	30 Nm	24..240 VAC/DC	40/60/90/120/150 sec. at 90°	~ 20 sec. at 90°	3-pos, 0...10 VDC, 4...20 mA	0...10 VDC, 4...20 mA	SB 5.0
InMax- 50 - YF	50 Nm	24..240 VAC/DC	40/60/90/120/150 sec. at 90°	~ 20 sec. at 90°	3-pos, 0...10 VDC, 4...20 mA	0...10 VDC, 4...20 mA	SB 5.0
InMax- ... - CTM	Type as above but with aluminium housing and Amercoat paint, gearbox parts in stainless steel, cable gland and hollow rivet nickel-plated						

## Application

Damper



Ball valve



Throttle valve



## Description size M Highlights

The new InMax actuators are a revolution for safety, control and shut-off dampers, VAV systems, ball valves, throttle valves and other motorized applications for HVAC systems, in chemical, pharmaceutical, industrial and Offshore-/Onshore plants, for use in safe areas.

IP66 protection, small dimensions, only 9,5 kg weight, universal functions and technical data, an integrated heater guarantee safe operation even under difficult environmental conditions. High quality brushless motors guarantee long life.

All actuators are programmable and adjustable on site. Special tools or equipment are not required. 5 motor running times, according to the actuator type, are selectable or adjustable on site. The integrated universal power supply is self adaptable to input voltages in the range of 24 to 240 VAC/DC.

The actuators are 100% overload protected.

InMax-...-YF actuators are equipped with spring return fail safe function. Standard shaft connection is a squared direct coupling with 16 x 16 mm. Different accessories are available to adapt aux. switches, terminal boxes or adaptations for ball valves and throttle.

- ▶ Industrial actuators
- ▶ Universal supply unit from 24 to 240 VAC/DC
- ▶ 5 different motor running times (40-60-90-120-150 sec./90°), adjustable on site
- ▶ Spring return fail safe operation in ~ 20 sec.
- ▶ 3-pos, 0...10 VDC, 4...20 mA control mode, with or without spring return function
- ▶ Feedback signal 0...10 VDC and 4...20 mA
- ▶ Reverse function
- ▶ 100 % overload protected
- ▶ Compact design and small dimension (L x W x H = 286 x 150 x 116 mm)
- ▶ Direct coupling to the damper shaft with squared connection 16 x 16 mm
- ▶ 95° Angle of rotation incl. 5° pre-tention
- ▶ Robust aluminium housing with IP66 protection
- ▶ Simple manual override include + preparation for comfortable manual override
- ▶ Gear made of stainless steel and sinter metal
- ▶ Only ~ 9,5 kg weight
- ▶ Integral heater for ambient temperatures down to -40°C
- ▶ Integral safety temperature sensor
- ▶ Integral equipment for manual adjustment (push button, lamp, switch)
- ▶ Preparation for adaptable aux. switches type InSwitch
- ▶ Range of accessories

Technical data	InMax-50.75-Y	InMax-100-Y	InMax-30-YF	InMax-50-YF
Torque motor	min. 50 / 75 Nm selectable on site	min. 100 Nm	min. 30 Nm	min. 50 Nm
Torque spring return (F)	without F	without F	min. 30 Nm	min. 50 Nm
Dimension of external torque	above mentioned torques are min. torques in blocked position, external torque should be max. 80 % of max. actuator torque but min. 15 Nm			
Supply voltage/Frequency	24...240 VAC/DC, ± 10 % , self adaptable, Frequency 50...60 Hz ± 20 %			
Dimension	max. starting currents see table (in acc. with voltage, I <sub>start</sub> >> I <sub>rated</sub> ), max. 20 W blocking position, approx. 16 W for heater			
Protection class	class I (grounded)			
Angle of rotation and indication	95°, incl. ~ 5° pre-tention, mechanical value indication			
Working direction	selectable by left/right mounting to the damper/valve shaft			
Motor running time	40 / 60 / 90 / 120 / 150 sec. at 90° selectable on site			
Motor	brushless DC Motor			
Spring return (F)	without F	without F	spring return in the event of loss of power	
Spring return running time (F)	without F	without F	spring return in ~ 20 sec. at 90°	
Safety operations (F)	without F	without F	min. 10.000 in acc. with construction of damper and ambient	
Control mode Y	3-pos, 0..10 VDC, 4...20 mA in acc. with wiring, selectable on site, galvanic separation between supply and signals			
Feedback signal U	0..10 VDC, 4...20 mA in acc. with wiring, selectable on site			
Resistance of Y and U signals	<b>Input signal</b> Yu 0...10 VDC @ 10 kΩ, Yi 4...20 mA @ 100 Ω. <b>Feedback signal</b> Uu 0...10 VDC @ 1.000...∞ Ω, Ui 4...20 mA @ 0..800 Ω			
Reverse function	bridge between wiring 3 and 4 (signal wise) gets a reverse function of Y and U			
Adjustment of Y and U	If the angel of rotation is different to 90° the input Y and output signal U can be adjusted to the new angel of rotation			
Axle of the actuator	squared 16 × 16 mm, direct coupling, 100 % overload protected			
Electrical connection	cable, ~1 m, diameter of wires 0,5 mm <sup>2</sup> , for electrical connection a terminal box is required!			
Diameter of cable	~ Ø 7,1 mm and ~ Ø 7,4 mm	~ Ø 7,1 mm and ~ Ø 7,4 mm	~ Ø 7,1 mm and ~ Ø 7,4 mm	~ Ø 7,1 mm and ~ Ø 7,4 mm
Cable gland	M16 × 1,5 mm standard			
Manual override	manual override only if supply voltage is cut, use delivered socket wrench, slow motion, enough torque/force is required <b>Attention:</b> with manual operation of the spring danger of injury exists, with release/let go the hexagonal spanner!			
Integral heater	integral heater, controlled, for ambient temperature down to -40°C			
Housing material and weight	aluminium die cast housing ~ 9,5 kg, painted (optional marine coating ...-CTM)			
Dimensions	L × W × H = 286 × 150 × 116 mm, for diagramm see extra information "ME"			
Ambients	storage temp. -40...+70°C, working temperature -40...+50°C			
Humidity	0...90 %rH, non condensing			
Operation mode	100 % ED			
Self adjustment	at initial system checkout for motor or rotation angle < 90° you need to start the self adjustment mode			
Maintenance	maintenance free, maintenance must be complied with regional standards, rules and regulations			
Wiring diagrams (SB)	<b>SB 4.0</b>	<b>SB 4.0</b>	<b>SB 5.0</b>	<b>SB 5.0</b>
Delivery	1 actuator, 1 m cable, squared shaft connection 16 × 16 mm, 4 × M8 × 140 mm screws, 4 nuts M8 socket wrench for simple manual override			
Parameter at delivery	50 Nm, 90 sec./90°	100 Nm, 90 sec./90°	30 Nm, 90 sec./90°	50 Nm, 90 sec./90°

Certification	InMax actuators – size M
EMV	2004/108/EC
Low voltage	2006/95/EC
IP-Protection	IP66, in acc. with EN 60529
Potential compensation	external PA-terminal, 4 mm <sup>2</sup>

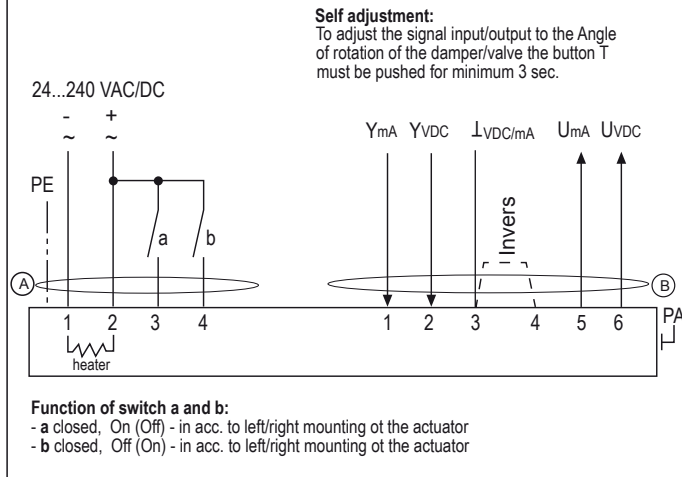
Accessories or special solutions – size M	
<b>InMax-.-CTM</b>	above listed types in aluminium box and Amercoat painted
<b>InBox-...</b>	Terminal boxes
<b>InSwitch</b>	2 external aux. switches, adjustable on site
<b>MKK-M</b>	mounting bracket for terminal boxes type InBox-... direct on actuator
<b>HV-M</b>	comfortable manual override for InMax actuators size M
<b>Adaptations</b>	various adaptations for dampers/valves on request
<b>AR-16-xx</b>	Reduction of square damper connection from 16 mm to 14, 12

**Electrical connection**

InMax actuators are equipped with a universal supply unit working at a voltage range from 24 to 240 VAC/DC. The supply unit is self adjustable to the connected voltage! The safety operation of the spring return function works if the supply voltage is cut.

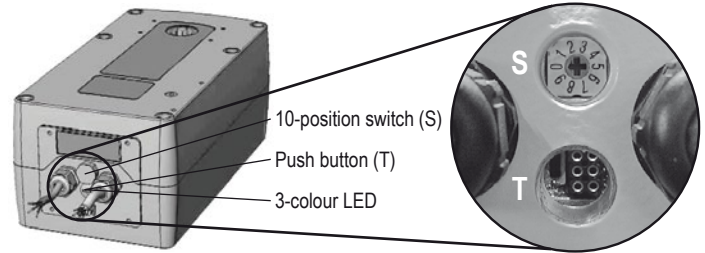
**Wiring diagram InMax-50.75-Y and InMax-100-Y**

**Continuous control or 3-pos without spring return SB 4.0**



**Parameter, Adjustment – Failure indication**

Switch – Push button – Lamp for adjustment, behind the blanking plug



**Parameter selection**

Example: InMax-50.75-Y

Requested parameter:

Torque 75 Nm  
Running time motor 90 sec/90°

Type	Torques	
InMax-50.75 -Y	50 Nm	75 Nm
InMax- 100 -Y	100 Nm	
InMax- 30 -YF	30 Nm	
InMax- 50 -YF	50 Nm	
Running times	Position of switch S	
40 sec./90°	00	05
60 sec./90°	01	06
90 sec./90°	02	07
120 sec./90°	03	08
150 sec./90°	04	09

Result: switch position (S) 07

**Function, adjustment and parameter**

**A) Self adjustment of Angle of rotation:**

Switch (S) into position 02 (low torque) or 07 (high torque), then push button (T) for minimum 3 seconds. The actuator will drive into both end positions to be adjusted. LED indicates green.

Adjustment time needs approx. 180 sec. (90 sec. On, 90 sec. Off). After that, switch S into position 00-09 in acc. with your required torque and running time.

**B) Selection of running time and torque:**

Put switch (S) into the correct/selected position in acc. to above table.

The selected parameter will work at next operation of the actuator.

Adjustment can be done even without supply voltage. If supply voltage is available turn switch only if actuator is not running.

**C) Running time spring return:**

Standard ~ 20 sec

**D) Change from modulating into 3-pos operation mode:**

Push button (T) 3 times. LED changes from green to yellow.

Push button within next limits:

- Push time min. 0,2 sec.

- The max. time for 3 push is 5 sec.

**E) Change from modulating into 3-pos operation mode:**

Push button (T) 3 times. LED changes from yellow to green.

**F) Additional information for 3-pos operation:**

a closed, b open = direction I

b closed, a open = direction II

a and b closed = Motor doesn't work

a and b opened = Motor doesn't work

Direction (I and II) depends on left/right mounting of the actuator to the damper/valve.

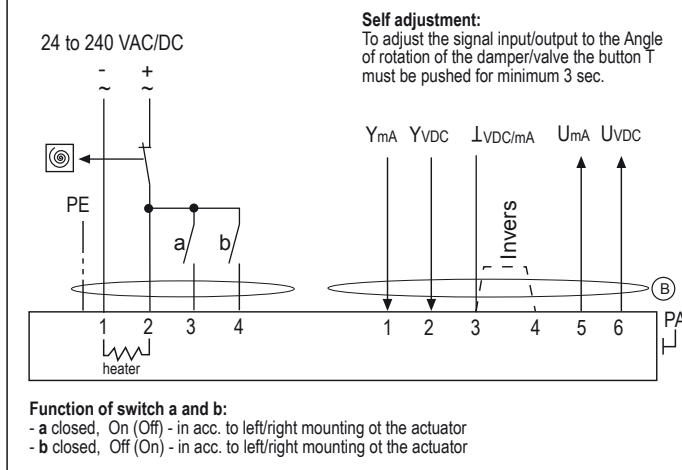
You can change direction of the motor by changing electrical wiring terminal 3 and 4.

**G) Reverse function:**

Bridge between wiring 3 and 4 (signal wise) gets a inverse function of Y and U.

**Wiring diagram InMax-30-YF and InMax-50-YF**

**Continuous control or 3-pos with spring return SB 5.0**



**Attention**

Never use actuators in spring return mode without external torque/force.

**Modulating- 3 pos- change**

LED	Status
GREEN	Supply available, Actuator active in modulating mode
YELLOW	Supply available, Actuator active in 3-pos mode

**Error indication**

See extra information "EL"

Mounting instructions and important information for operation and installation

**Important information for installation and operation**

**A. Installation, commissioning, maintenance**

The cable of the actuator must be installed in a fixed position and protected against mechanical and thermal damage. In acc. with operation InMax actuators are maintenance free.

The actuators must not be opened by the customer. For outdoor installation a protective housing against rain, snow and sun should be applied to the actuator, as well as a constant supply at terminal 1 and 2 for the integral heater.

**B. Shaft connection, selection of running time, heater**

InMax actuators are equipped with a direct coupling squared shaft connection of 16 x 16 mm. The housing of the actuator is axially symmetrically built to select open/close direction of the spring return function by left/right mounting.

In acc. to the actuator type 5 different motor running times can be selected on site. The integral heater is for ambient temperatures down to -40°C.

**C. Minimum load**

Minimum load not less than 20% of the rated torque, min. 10 Nm

**D. 3-pos control mode**

See extra information "EL".

**E. Spring return**

Spring return function works if the supply voltage (terminal 1 or 2) is cut. In the event of an electrical interruption, the spring returns to its end position.

**F. Operation at an ambient temperature below -20°C**

See extra information "EL".

**G. Excess temperature**

InMax actuators are equipped with an additional temperature sensor to stop the actuator before reaching this max. temperature. In this case the failure must be eliminated immediately on site.

**H. Synchronous mode**

To link two or more actuators together is not permitted.

**Extra information "EL" (see additional data sheet)**

extra technical information, versions of circuit diagrams and failure indication

**Extra information "ME" (see additional data sheet)**

extra technical information, dimensions, installation instruction and illustration

**Mounting on air dampers with double squared shaft connection**



Details see extra information "ME".

**Mounting of quarter turn valves**



Details see extra information "ME".

**InSwitch – adaptable external aux. switches**



InSwitch is an accessory to InMax actuators size M, fixing directly onto the actuator. InSwitch are aux. switches with with 2 potential free contacts, adustable on site.

**InBox – adaptable terminal box**



For electrical connection of an InMax actuator. **InBox-Y/S** for InMax-50.75, ..-100, ..-30-YF, ..-50-YF To adapt the InBox direct to the actuator housing an additional accessory **type MKK-M** is required.

# InMax – extra information EL-M



The „EL“ data sheet contains additional information for InMax actuators of the size „M“, for the optimization and simplification in regard to planning, installation and initial startup. It provides influences of external factors in reference to the safe initiation of the actuators, as well as technical references and problem solutions (error indication). With the error indication, functions can be examined and different error/problems can be adjusted locally.

- ▶ Power supply design
- ▶ Design of line cross section 24...48 VAC/DC
- ▶ Wiring alternatives for on-off, 3-pos, BF actuators
- ▶ Wiring alternatives for modulating actuators
- ▶ Use at ambient temperatures down to -20°C / -40°C
- ▶ Error indication – problem treatment/solution

For additional mechanical data have a look at extra information „ME-M“

## Power input depending of supply voltage

### Power supply design

The design of the on-site supply, depends on the selected motor running time and selected supply voltage. Accompanying values are „about values“, since there can be construction unit dispersions within electronics. The power consumption in the blocking position is run time independently with max. 20 W. The power consumption for the heater is between 5 and 12 W. The heading is running only if the motor is in idle position! The initial starting supply voltage required by the actuators power supply unit is around 2,0 A at 24 V for about 1 Sec. (Please consider this while conceiving the cross section of the supply line)

Voltage	Current	Rated current in acc. with motor running time				
		40s	60s	90s	120s	150s
240 V	I <sub>rated</sub>	0,3 A	0,3 A	0,15 A	0,10 A	0,10 A
24 V	I <sub>rated</sub>	1,0 A	0,7 A	0,5 A	0,4 A	0,4 A

Voltage	Current	Rated current in acc. with motor running time (Spring return)				
		40s	60s	90s	120s	150s
240 V	I <sub>rated</sub>	0,4 A	0,3 A	0,15 A	0,10 A	0,10 A
24 V	I <sub>rated</sub>	2,0 A	1,8 A	1,4 A	1,4 A	1,4 A

## Dimensioning of the line cross section with 24...48 VAC/DC supply voltages

### Dimensioning / Design of the supply line

On long distances between voltage supply and drive, voltage drops occur due to line resistances. As a consequence with 24 VAC/DC the actuator receives a too low tension and does not start. In order to prevent this, the cross section of the inlet line is to be designed/dimensioned accordingly. The accompanying formula allows the calculation of the necessary line cross section, perhaps provides the maximally permitted conduit length utilizing the existing line cross section. Alternatively the secondary voltage can be increased by selecting a transformer. For calculation purposes, following characteristics are essential:  
 U<sub>v</sub> = supply voltage in [V]  
 A = line cross section in [mm<sup>2</sup>]  
 L = conduit length in [m]  
 Factor 0.0714 = drive-specific factor  
 [Vmm<sup>2</sup>/m] (based on the electrical conductivity of electrolytic copper with a coefficient of 56m/Wmm<sup>2</sup>)

Formula for max. cable length "L" at cable cross section "A"

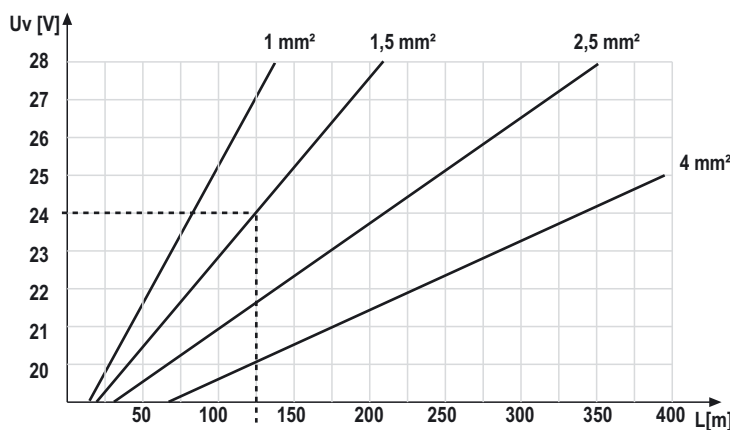
$$L = A \cdot (U_v - 18V) : 0,0714$$

Example: A = 1,5 mm<sup>2</sup>, U<sub>v</sub> = 24 V  
Length of cable L = 126 m

Formula of needed cable cross section "A" at a cable length of "L"

$$A = 0,0714 \cdot L : (U_v - 18V)$$

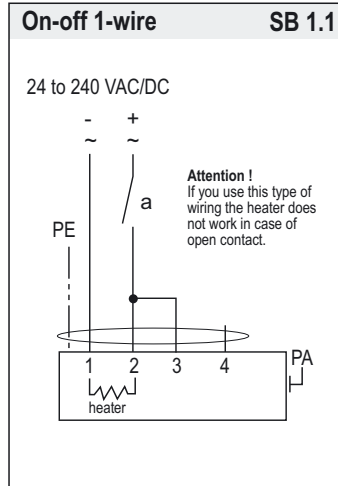
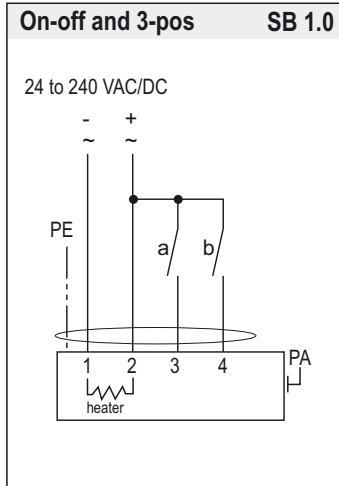
Example: L = 250 m, U<sub>v</sub> = 30 V  
Cross section of A = 1,5 mm<sup>2</sup>



Example:  
24 V power supply with wire diameter 1,5 mm<sup>2</sup> = 126 m

## Wiring alternatives for on-off and 3-pos actuators with spring return

**InMax-...-F, InMax-...-SF**



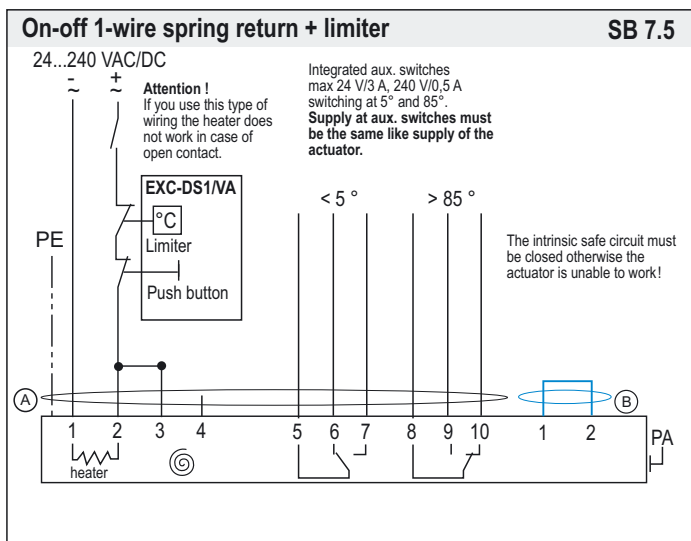
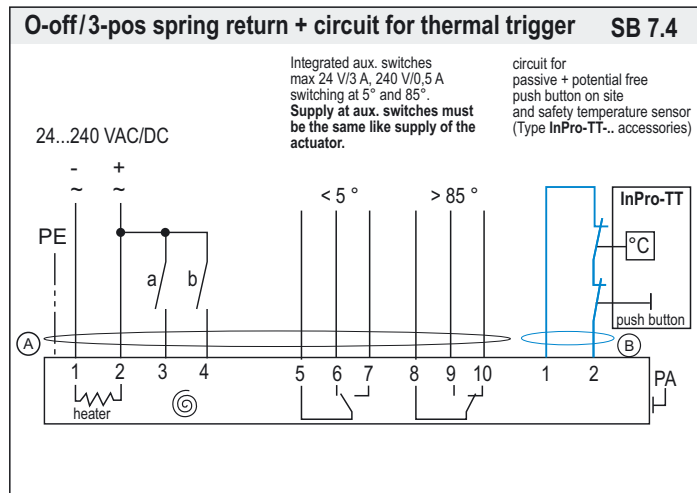
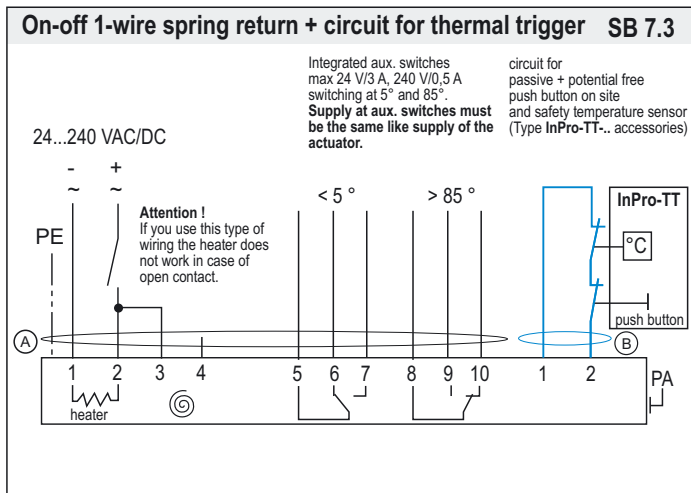
**Attention**

If 40 sec. or 60 sec. mode is selected for motor and/or spring return, the self adjustment of angle of rotation must be started.

Never use actuators without external torque/force min. 10 Nm.

## Wiring alternatives for BF actuators

**InMax-...-BF**



**Attention**

If 40 sec. or 60 sec. mode is selected for motor and/or spring return, the self adjustment of angle of rotation must be started.

Never use actuators without external torque/force min. 10 Nm.

## Wiring alternatives for modulating actuators with or without spring return

### InMax...-Y..

**Modulating or 3-pos with/without spring return SB 4.0**

24...240 VAC/DC

Self adjustment:  
To adjust the signal input/output to the Angle of rotation of the damper/valve the button T must be pushed for minimum 3 sec.

Function of switch a and b:  
- a closed, On (Off) - in acc. to left/right mounting of the actuator  
- b closed, Off (On) - in acc. to left/right mounting of the actuator

Reverse function: ①  
bridge 3 up 4 reverse input and output signals.

**Modulating with/without spring return SB 4.1**

24...240 VAC/DC

Self adjustment:  
To adjust the signal input/output to the Angle of rotation of the damper/valve the button T must be pushed for minimum 3 sec.

Reverse function: ①  
bridge 3 up 4 reverse input and output signals.

**Modulating with/without spring return, no feedback SB 4.2**

24...240 VAC/DC

Self adjustment:  
To adjust the signal input/output to the Angle of rotation of the damper/valve the button T must be pushed for minimum 3 sec.

Reverse function: ①  
bridge 3 up 4 reverse input and output signals.

**3-pos with/without spring return, plus feedback SB 4.3**

24...240 VAC/DC

Self adjustment:  
To adjust the signal input/output to the Angle of rotation of the damper/valve the button T must be pushed for minimum 3 sec.

Function of switch a and b:  
- a closed, On (Off) - in acc. to left/right mounting of the actuator  
- b closed, Off (On) - in acc. to left/right mounting of the actuator

Reverse function: ①  
bridge 3 up 4 reverse input and output signals.

### Over temperature, 3-pos-operation, heating by low ambient temperatures

**I. Temperature rise**  
While operating the actuator following parameters have to be aligned:  
At overload resp. temperature rise the actuator will remain functionless until cooling.  
During cooling the LED is red.

**II. 3-pos operation**  
Actuators are in the best way suitable for the 3-pos operation. To protect such elements as gears and mounting elements against harmful influences like minimum pulse time, actuators are protected via internal electronics. The internal electronic permits impulses > 0,1 sec., the pulse length must be 0,5 sec. By shift in direction the interval is 1 sec.

**III. Use at low ambient temperature below -20°C**  
All actuators are equipped with a regulated integrated heating device designed for employments down to -40°C ambient temperature.  
The heater will be supplied automatically by connecting the constant voltage supply on the clamps 1 and 2.  
Following parameters are to be considered by ambient temperature < 10°C:  
1. After mounting the actuator must be immediately electrically connected.  
2. The actuator will only be activated after the operating temperature has reached at least -20°C.  
3. The adjustment options are only ensured after this heating up period.

**IV. Mechanical protection**  
1. The actuator must be operated with an outside load of at least 10 Nm.  
2. After installing the actuator to the damper/armature an automatic alignment has to be accomplished, in order to obtain a "gentle blockade/stop". This function protects the damper/armature by reducing the end positions/blockade speed in order to avoid mechanical overload. The actuator aligns specifically once with 90 Sec/90° onto each position, recognizes the blockade position in order to reduce the motor performance during operation briefly before reaching the end/blockade position.

## Error indication

Error/Symptom	Reason	Solution
01 Actuator does not work LED does not lights	<ul style="list-style-type: none"> <li>No power supply attached</li> <li>The actuator is operated beyond ex-prevention ambient temperature specifications and the internal temperature sensor did irreversibly shut down operations</li> </ul>	<ul style="list-style-type: none"> <li>Attache power supply and turn on</li> <li>Because of inadmissible operation the actuator drove out of safety relevant reasons into an irreversible condition and must be exchanged. Accompanying new installation the ambient temperature has to be reduced accordingly</li> </ul>
02 Actuator does not work LED lights red	<ul style="list-style-type: none"> <li>The actuator is operated by a too high ambient temperature and the internal temperature sensor responded</li> </ul>	<ul style="list-style-type: none"> <li>Shut off actuator and let temperature decrease, reduce ambient temperature by suitable measures e.g. ventilation or other mounting position of the actuator</li> </ul>
03 Actuator does not work LED lights green	<ul style="list-style-type: none"> <li>3-Pos control signal is wired on both entrances</li> <li>Required torque is greater than actuators torque</li> <li>Control signals are not attached or attached on a wrong conductor</li> <li>Actuator is incorrect mounted and is blocked by an external stop unit</li> <li>Interchanged supply lines</li> </ul>	<ul style="list-style-type: none"> <li>Readjust/correct circuit</li> <li>Adjust a higher torque at the actuator if possible otherwise exchange for a type with higher torque.</li> <li>Examine rule and adjusting signal in accordance with attached diagram</li> <li>Dismount actuator and testdrive without load for operability. Install actuator accordingly that the power transmissions runs without external blockade or torsion</li> <li>Wire 1 must be (-, N) and wire 2 (+, L)</li> </ul>
04 Actuator does not work LED is red blinking	<ul style="list-style-type: none"> <li>The actuator has been mounted by temperatures of less than -20°C and did not reach is operating temperatur of at least -20°C.</li> </ul>	<ul style="list-style-type: none"> <li>Ensure that a constant voltage supply on conductor 1--2 is existing.</li> <li>Wait until the required operating temperature is achieved by the actuators internal heating system. The actuator will start operating independently</li> </ul>
05 Y-drive in the 3-pos mode can not gear into intermediate positions	<ul style="list-style-type: none"> <li>The conversion of constant mode on 3-pos-modus was not set</li> </ul>	<ul style="list-style-type: none"> <li>Recalibrate the actuator in accordance with assembly instructions</li> </ul>
06 Actuator sits diagonally on the squared damper shaft	<ul style="list-style-type: none"> <li>The actuators have an angle of rotation of 95° inclusive 5° pre-tention. While assembling the pre-loading was not considered</li> </ul>	<ul style="list-style-type: none"> <li>Dismount actuator of the damper, use the enclosed socket wrench to draw up approx. 5° over the hand operated control device before remounting on the damper shaft. Consider additional information ME-M of the assembly instructions</li> </ul>
07 A modulating actuator (Y) works with reduced angle of rotation and already reaches its end positions before 0 V/4 mA, respectively before 10V/20mA.	<ul style="list-style-type: none"> <li>At start up no self adjustment of angle of rotation was accomplished</li> </ul>	<ul style="list-style-type: none"> <li>Accomplish self adjustment of angle of rotation in accordance with assembly instruction</li> </ul>
08 LED flashes irregularly and actuator does not work	<ul style="list-style-type: none"> <li>Actuator does not receive sufficient supply voltage</li> <li>Cable to long, voltage drop in the supply line to large</li> </ul>	<ul style="list-style-type: none"> <li>Increase line cross section or increase tension at the transformer/power supply unit</li> <li>Increase line cross section or increase tension</li> </ul>



# InMax – extra information ME-M



The „ME-M“-data sheet contains additional information for InMax actuators of the size „M“, for the optimization and simplification in regard to planning, installation and initial start up. It provides influences of external factors in reference to the safe initiation of the actuators. In particular it represents the installation, as well as different dampers, fire dampers and armatures. Additionally describing different accessory elements and their mounting to the actuator.

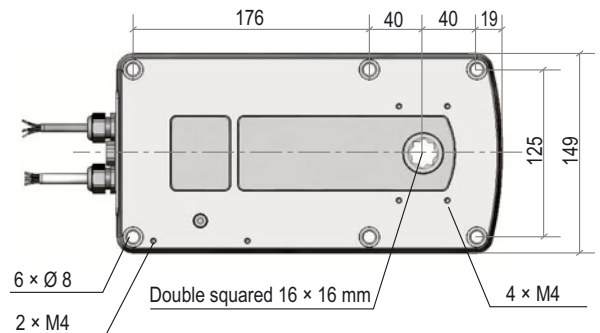
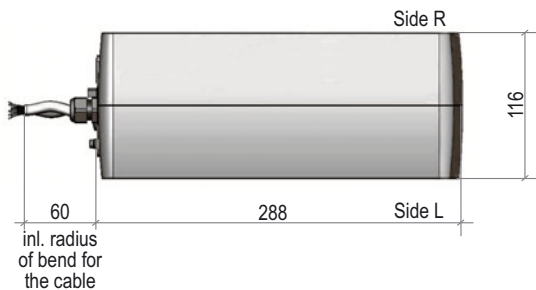
- ▶ Dimension, drill template
- ▶ Control elements: switch – push button – LED
- ▶ Outdoor installation
- ▶ Mounting using form-fitting shaft connection (square shaft)
- ▶ Mounting on butterfly valves and ball valves
- ▶ Mounting InBox, InSwitch

For additional electrical data have a look at extra information „EL“

## Dimensions – drill template

### Dimension size M

Dimension in mm

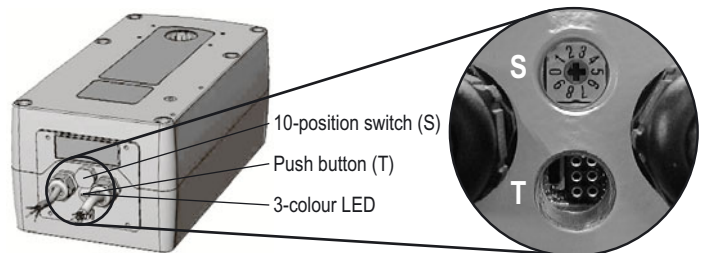


## Control elements: switch – push button – LED

### Specification

All InMax actuators are equipped with a 10 position switch a push button and a multicolor LED calibration. These control elements are to be found cable-laterally behind the two middle sectioned dummy plugs. For operation these must be removed. The calibration can be achieved despite lining up tension at the actuator. It has to be of great concern that the dummy plugs must be rescrewed in order to comply with the IP-protection class. The operation of the switch and button has to be done by means of a small screwdriver. Force with strong pressure and /or rotation is to be avoided in any case, since otherwise control electronics can be damaged irreparably. By bad visibilities a flashlight should be used. Attitudes of torque and running time can be achieved also before mounting. The adjustment of angle of rotation can be started only with an outside load and accurate mounting.

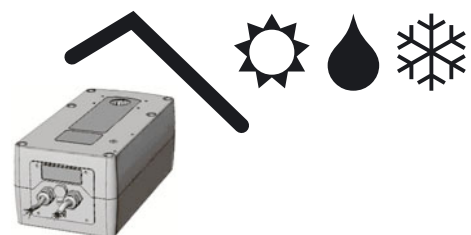
Switch – push button – LED for programming, behind dummy plug



## Outdoor installation

### Specification

For outdoor installation it has to be certain that the actuator is protected against direct sun exposure (heat and UV), rain and snow by employing an enclosure roof. Supply voltage is to be applied immediately after mounting in order to assure integrated heating at start. Since explosion proof actuators must have internal safety temperature limiters, these may not be exposed neither at storage nor during operation to a too high temperature. Otherwise the limiters could respond and switch of the actuator irreversibly.



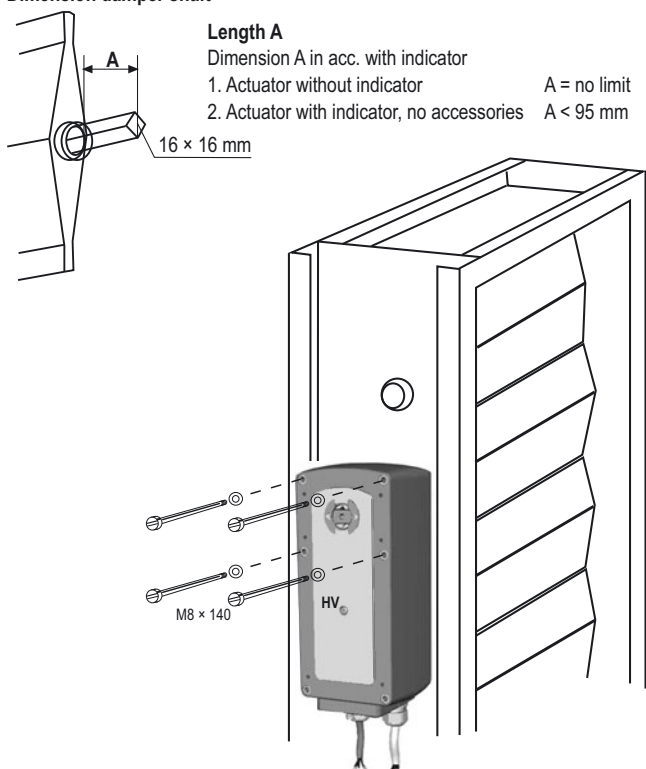
## Mounting instruction for InMax actuators size M on air dampers

### Specification

InMax actuators size M are equipped with a 16 × 16 mm (double square) shaft connection. The form-fitting shaft connection is the securest connection between damper shaft. The actuator will be connected firmly by means of four screws M 8 × 140 (scope of supply) to the damper.

### Form fitting mounting on square damper shaft

#### Dimension damper shaft



4 screws M8 × 140, as well as a socket wrench, are part of delivery for InMax actuators size „M“.

For damper shafts 14 × 14 or 12 × 12 mm reducing bush are optional available.



### Mounting instructions form-fitting shaft connection

It is to be considered that the actuators have a total angle movement of approx. 95° in order to realize a pre-tension on the damper. Therefore the actuator sits tilted on the damper shaft. In order to prevent this and to assure pre-tension to the damper the driving shaft has to be adjusted mechanically before connecting to the damper shaft.

The provided socket wrench serves for the mechanical adjustment over the hand-operated control socket HV. The actuators are axially symmetrically developed. In case of spring return function the safety position must be selected by turning the actuator 180°.

#### Mounting:

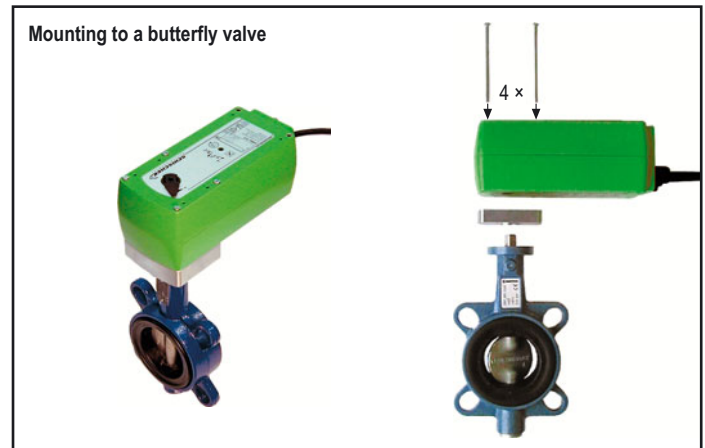
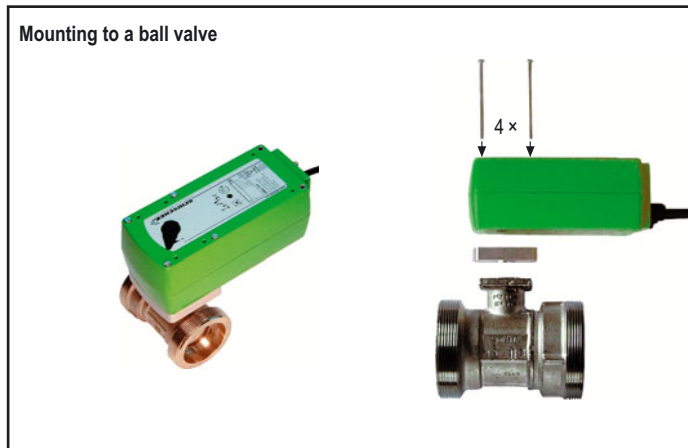
1. Affix tap hole M8 (in accordance with drill template) on the damper or to a mounting bracket.
2. Adjust drive shaft of the actuator with the socket wrench that the drive stands perpendicular to the damper before plugging actuator on to the damper shaft.
3. Plug actuator onto damper shaft and fix diagonally with 2 screws.
4. Remove the socket wrench.
5. Pivot and tighten the remaining screws.

**Note:** the drive shaft is selflocking produced and may only be mechanically adjusted either with the provided socket wrench or the optional accessory „HV-M“ manual override. External applied force to the shaft can lead to mechanical damage of the actuator.

## Mounting instructions for InMax actuators size M on butterfly valve and ball valve

### Specification

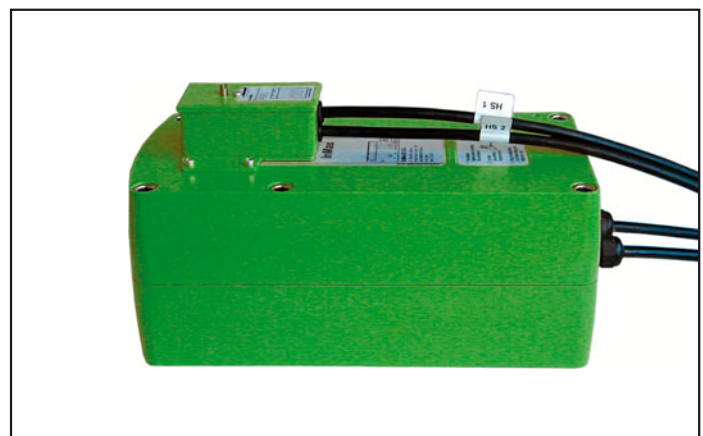
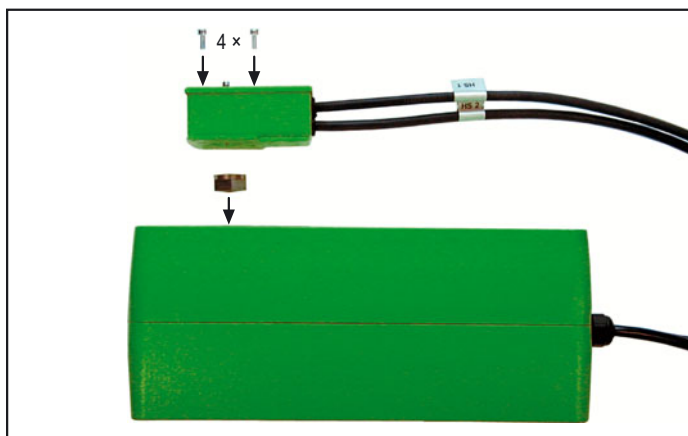
InMax actuators of the size M are equipped with a 16 × 16 mm (double square) form-fitting shaft connection. For mounting to butterfly valves or ball valve a special mounting bracket in acc. with DIN EN ISO 5211 is required. Since this standard provides only certain basic conditions there can be substantial geometrical differences between armatures which require a special adaption.



## Mounting of InSwitch accessory to the actuator

### Specification

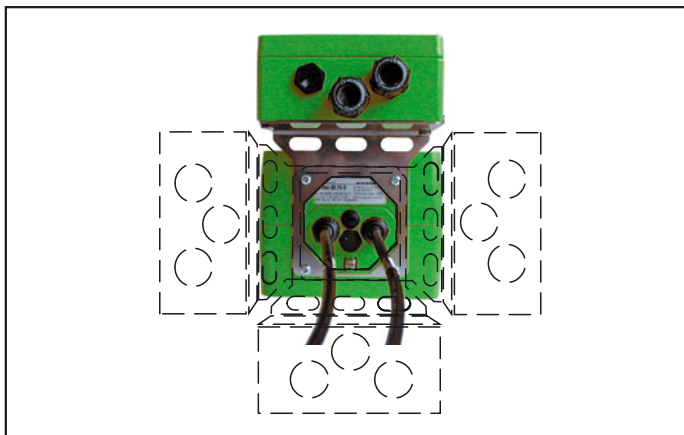
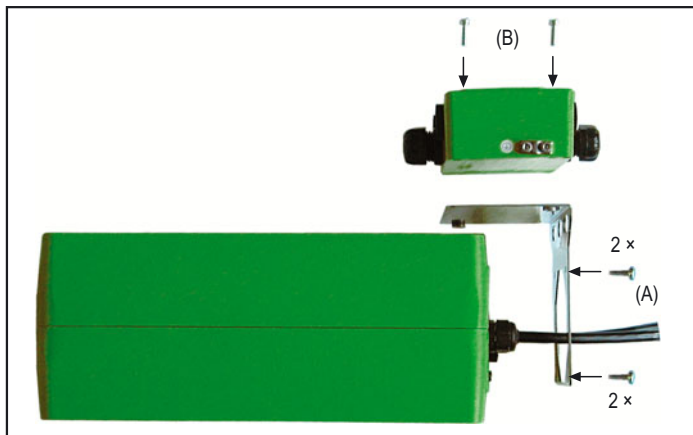
1. Put the squared connection part to the actuator, then mount InSwitch and fix it with 4 screws
2. InMax with mounted InSwitch



## Mounting of terminal boxes type InBox via mounting bracket type MKK-M to the actuator (accessory)

### Specification

1. Screw mounting bracket to the actuator (A) then terminal box to the mounting bracket (B) screws      Mounting bracket MKK-M can be mounted every 90°



Terminal box mounted above the actuator

Terminal box mounted beside the actuator

